

Emotron VS30 AC drive 3 ... 7.5 kW





Mounting and switch on instruction





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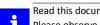


1 **General information**

First read, then start

1 **General information**

1.1 First read, then start



Read this documentation thoroughly before carrying out the installation and commissioning. Please observe the safety instructions!



Information and tools with regard to the Emotron products can be found on the Internet: http://www.emotron.com/services-support/file-archive

1.2 Notations and conventions

1.2.1 Product code Emotron, examples:

VS30-40-7P3-20-C

VS30-40-016-20-M

| VS | 30 | 40 | /P3 | 20 | C |
|--------|---------|------|--------------------|------|-------------------|
| Series | 3-phase | 400V | Rated current 7.3A | IP20 | CANopen + STD I/O |
| VS | 30 | 40 | 016 | 20 | M |
| Series | 3-phase | 400V | Rated current 16A | IP20 | MODBUS + STD I/O |
| | | | | | |

2 Safety instructions

2.1 Basic safety measures

Disregarding the following basic safety measures may lead to severe personal injury and damage to material assets!

The product

- · must only be used as directed.
- must never be commissioned if they display signs of damage.
- · must never be technically modified.
- · must never be commissioned if they are not fully mounted.
- must never be operated without required covers.

Connect/disconnect all pluggable terminals only in deenergised condition. Only remove the product from the installation in the deenergised state.

Insulation resistance tests between 24V control potential and PE: According to EN 61800–5–1, the maximum test voltage must not exceed 110 VDC.

Observe all specifications of the corresponding documentation supplied. This is the precondition for safe and trouble-free operation and for obtaining the product features specified.

The procedural notes and circuit details described in this document are only proposals. It is up to the user to check whether they can be adapted to the particular applications. Emotron does not take any responsibility for the suitability of the procedures and circuit proposals described.

The product must only be used by qualified personnel. IEC 60364 or CENELEC HD 384 define the skills of these persons:

- They are familiar with installing, mounting, commissioning, and operating the product.
- They have the corresponding qualifications for their work.
- They know and can apply all regulations for the prevention of accidents, directives, and laws applicable
 at the place of use.

Observe the specific notes in the other chapters!

2 Safety instructions

Residual hazards

2.2 Residual hazards

The user must take the residual hazards mentioned into consideration in the risk assessment for his/her machine/system.

If the above is disregarded, this can lead to severe injuries to persons and damage to material assets!

Product

Observe the warning labels on the product!

| 1 | Description |
|----------|--------------------------------------------------------------------------------------------------|
| | Electrostatic sensitive devices: |
| 1 | Before working on the inverter, the staff must ensure to be free of electrostatic charge! |
| ^ | Dangerous electrical voltage |
| 14 | Before working on the inverter, check whether all power connections are dead! After mains OFF, |
| 4 | power con- nections X100 and X105 carry a dangerous electrical voltage for the time specified on |
| Λ | High leakage current: |
| <u> </u> | Carry out fixed installation and PE connection in compliance with EN 61800–5–1 or EN 60204–1! |
| Λ | Hot surface: |
| <u> </u> | Use personal protective equipment or wait until devices have cooleddown! |

Motor

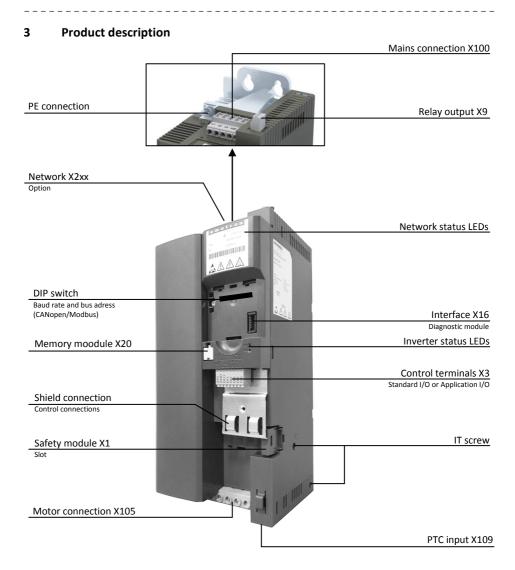
If there is a short circuit of two power transistors, a residual movement of up to 180° /number of pole pairs can occur at the motor! (For 4-pole motor: residual movement max. $180^{\circ}/2 = 90^{\circ}$).

This residual movement must be taken into consideration by the user for his/her risk assessment.

2.3 Application as directed

The product

- must only be actuated under the operating conditions prescribed in this documentation.
- meets the protection requirements of 2014/35/EU: Low-Voltage Directive.
- is not a machine in terms of 2006/42/EC: Machinery Directive.
- is not a household appliance, but is only designed as component for commercial or professional use in terms of EN 61000-3-2.



4 Mounting

4.1 Important notes

⚠ DANGER!

Dangerous electrical voltage

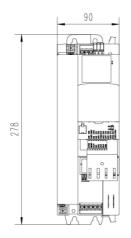
Possible consequence: death or severe injuries

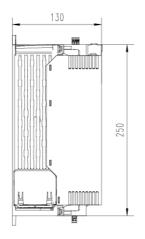
- ▶ All works on the inverter must only be carried out in the deenergised state.
- After switching off the mains voltage, wait for at least 3 minutes before you start working.

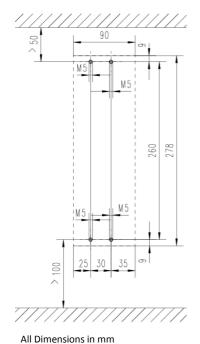
4 **Mounting** Important notes

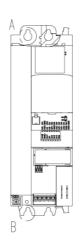
4.2 Mechanical installation

Dimensions 3 kW ... 5,5 kW

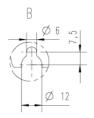








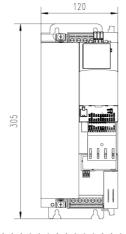


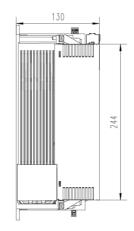


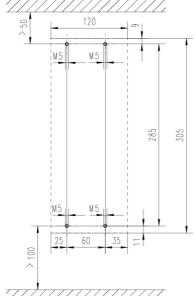
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Mechanical installation

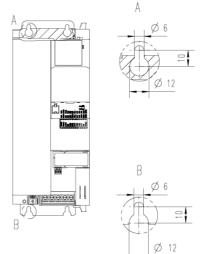
Dimensions 7,5 kW







All Dimensions in mm



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4 Mounting Electrical installation Connection to the 400 V system

4.3 Electrical installation

4.3.1 Connection to the 400 V system

4.3.1.1 Connection plan

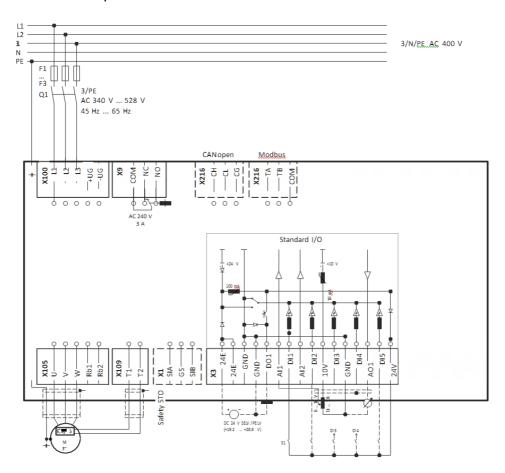


Fig. 1: Wiring example

S1 Start enable

--- Dashed line = options

4.3.1.2 Fuses and cable cross-sections Operation

without mains choke

Cable installation in compliance with EN 60204-1 Laying system B2

| Inverter | | VS30407P3 | VS30409P5 | VS3040013 | VS3040016 | |
|---------------------|-----|--------------|-----------|-----------|-----------|--|
| Rated power | kW | 3 | 4 | 5,5 | 7,5 | |
| Rated mains current | | | | | | |
| without mains choke | Α | 9,6 | 12,5 | 17,2 | 20 | |
| Fuse | | | | | | |
| Characteristics | | gG/gL or gRL | | | | |
| Max. rated current | Α | 25 | 25 | 25 | 32 | |
| Cable cross-section | mm² | 6 | 6 | 6 | 10 | |
| Circuit breaker | | | | | | |
| Characteristics | | В | | | | |
| Max. rated current | Α | 25 | 25 | 25 | 32 | |
| Cable cross-section | mm² | 6 | 6 | 6 | 10 | |

4.3.1.3 Terminal data Mains

connection

| Inverter | | VS30407P3 | VS30409P5 | VS3040013 | VS3040016 | | | |
|--------------------------|-----|----------------|-----------|-----------|-----------|--|--|--|
| Rated power | kW | 3 | 4 | 5,5 | 7,5 | | | |
| Connection | | | Х | 100 | | | | |
| Connection type | | Screw terminal | | | | | | |
| Min. cable cross-section | mm² | 1,5 | | | | | | |
| Max. cable cross-section | mm² | 6 | | 16 | 35 | | | |
| Stripping length | mm | 9 | | 11 | 18 | | | |
| Tightening torque | Nm | 0,5 | | 1,2 | | | | |
| Required screwdriver | | 0.6 x | 3.5 | 0.8 x 4.0 | 0,8 x 5.5 | | | |

Motor connection

| Inverter | | VS30407P3 | VS30409P5 | VS3040013 | VS3040016 | | |
|--------------------------|-----|----------------|-----------|-----------|-----------|--|--|
| Rated power | kW | 3 | 4 | 5,5 | 7,5 | | |
| Connection | | | Х | 105 | | | |
| Connection type | | Screw terminal | | | | | |
| Min. cable cross-section | mm² | 1,5 | | | | | |
| Max. cable cross-section | mm² | 6 | i | 16 | 35 | | |
| Stripping length | mm | 9 | | 11 | 18 | | |
| Tightening torque | Nm | 0,5 | | 1,2 | 3.8 | | |
| Required screwdriver | | 0.6 x | 3.5 | 0.8 x 4.0 | 0.8 x 5.5 | | |

4

Mounting Electrical installation Connection to the 400 V system

PE conductor connection

| Inverter | | VS30407P3 | VS30409P5 | VS3040013 | VS3040016 | | |
|--------------------------|-----|-----------|-----------|-----------|-----------|--|--|
| Rated power | kW | 3 | 4 | 5,5 | 7,5 | | |
| Connection | | | P | E | | | |
| Connection type | | PE screw | | | | | |
| Min. cable cross-section | mm² | 1,5 | | | | | |
| Max. cable cross-section | mm² | | 6 | | 16 | | |
| Stripping length | mm | | 10 | | 11 | | |
| Tightening torque | Nm | 1,2 | | | 3,4 | | |
| Required screwdriver | | 0.8 x 5.5 | | | PZ2 | | |

Control connections

| Terminal description | | Relay output | PTC input | Control terminals |
|--------------------------|-----|----------------|----------------|-------------------|
| Connection | | Х9 | X109 | Х3 |
| Connection type | | Screw terminal | Screw terminal | Spring terminal |
| Min. cable cross-section | mm² | 0,5 | 0,5 | 0,5 |
| Max. cable cross-section | mm² | 1,5 | 1,5 | 1,5 |
| Stripping length | mm | 6 | 6 | 9 |
| Tightening torque | Nm | 0,2 | 0,2 | = |
| Required screwdriver | | 0.4 x 2.5 | 0.4 x 2.5 | 0.4 x 2.5 |

4.3.2 Connection to the IT system

i NOTICE!

Internal components have earth potential if the IT screws are not removed. Consequence: the monitoring functions of the IT system respond.

▶ Before connection to an IT system be absolutely sure to remove the IT screws.



4.3.3 CANopen connection

4.3.3.1 Connection plan

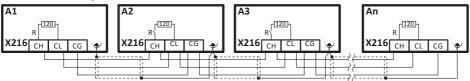


Fig. 2: Wiring example: CANopen network

4.3.3.2 Terminal data

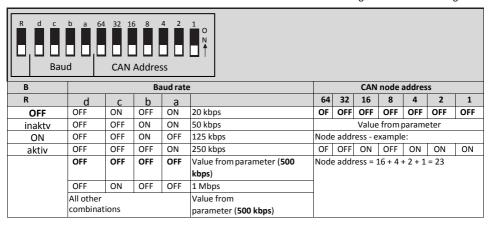
| Terminal description | | CANopen |
|--------------------------|-----|-----------------|
| Connection | | X216 |
| Connection type | | Spring terminal |
| Min. cable cross-section | mm² | 0,5 |
| Max. cable cross-section | mm² | 1,5 |
| Stripping length | mm | 10 |
| Tightening torque | Nm | - |
| Required screwdriver | | 0.4 x 2.5 |

4.3.3.3 Basic network settings

i

The network must be terminated with a 120 Ω resistor at the physically first and last node. Set the "R" switch to ON at these nodes.

Use the DIP switch to set the node address and baud rate and to activate the integrated bus terminating resistor.



Printed in bold = Emotron setting

4.3.4 Modbus connection

4.3.4.1 Connection plan

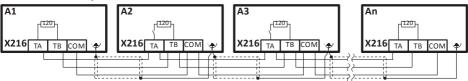


Fig. 3: Wiring example: Modbus network

4.3.4.2 Terminal data

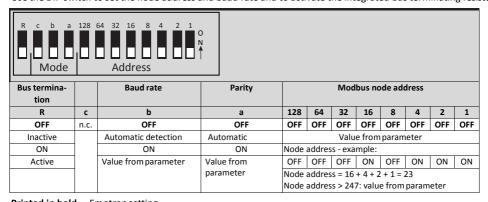
| Terminal description | | Modbus | |
|--------------------------|-----|-----------------|--|
| Connection | | X216 | |
| Connection type | | Spring terminal | |
| Min. cable cross-section | mm² | 0,5 | |
| Max. cable cross-section | mm² | 1,5 | |
| Stripping length | mm | 10 | |
| Tightening torque | Nm | - | |
| Required screwdriver | | 0.4 x 2.5 | |

4.3.4.3 Basic network settings

i

The network must be terminated with a 120 Ω resistor at the physically first and last node. Set the "R" switch to ON at these nodes.

Use the DIP switch to set the node address and baud rate and to activate the integrated bus terminating resistor.



Printed in bold = Emotron setting

4.3.5 Connection of the safety module

4.3.5.1 Important notes

A DANGER!

Improper installation of the safety engineering system can cause an uncontrolled starting action of the drives.

Possible consequences: Death or severe injuries

- Safety engineering systems may only be installed and commissioned by qualified and skilled personnel.
- All control components (switches, relays, PLC, ...) and the control cabinet must comply with the requirements of the EN ISO 13849–1 and the EN ISO 13849–2.
- Switches, relays with at least IP54 enclosure.
- Control cabinet with at least IP54 enclosure.
- It is essential to use insulated wire end ferrules for wiring.
- All safety relevant cables outside the control cabinet must be protected, e.g. by means of a cable duct
- Ensure that no short circuits can occur according to the specifications of the EN ISO 13849–2.
- All further requirements and measures can be obtained from the EN ISO 13849–1 and the EN ISO 13849–2.
- If an external force acts upon the drive axes, additional brakes are required. Please observe that hanging loads are subject to the force of gravity!
- The user has to ensure that the inverter will only be used in its intended application within the specified environmental conditions. This is the only way to comply with the declared safety-related characteristics.

A DANGER!

With the "Safe torque off" (STO) function, no "emergency stop" in terms -EN 60204–1 can be executed without additional measures. There is no isolation between the motor and inverter, no service switch or maintenance switch!

Possible consequence: death or severe injuries

"Emergency stop" requires electrical isolation, e.g. by a central mains contactor.

🛕 DANGER!

Automatic restart if the request of the safety function is deactivated. Possible consequences: Death or severe injuries

You must provide external measures according to EN ISO 13849-1 which ensure that the
drive only restarts after a confirmation.

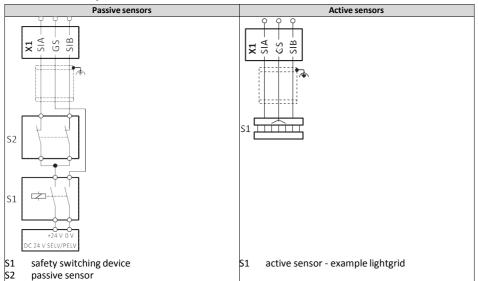
i NOTICE!

Overvoltage

Destruction of the safety component

 The maximum voltage (maximum rated) at the safety inputs is 32 V DC. The user must make provisions to avoid that this voltage is exceeded. _____

4.3.5.2 Connection plan



4.3.5.3 Terminal data

| Terminal description | | Safety STO |
|--------------------------|-----|----------------|
| Connection | | X1 |
| Connection type | | Screw terminal |
| Min. cable cross-section | mm² | 0,5 |
| Max. cable cross-section | mm² | 1,5 |
| Stripping length | mm | 6 |
| Tightening torque | Nm | 0,2 |
| Required screwdriver | | 0.4 x 2.5 |

| X1 | Specification | Unit | min. | typ. | max. |
|----------|-----------------------------------------|------|------|------|------|
| SIA, SIB | LOW signal | V | -3 | 0 | +5 |
| | HIGH signal | V | +15 | +24 | +30 |
| | Running time | ms | | 3 | |
| | Input current SIA | mA | | 10 | 14 |
| | Input current SIB | mA | | 7 | 12 |
| | Input peak current | mA | | 100 | |
| | Tolerated test pulse | ms | | | 1 |
| | Switch-off time | ms | | 50 | |
| | Permissible distance of the test pulses | ms | 10 | | |
| GS | Reference potential for SIA and SIB | | | | |

4 Mounting

Electrical installation
Connection of the safety module

5 Commissioning

5.1 Important notes



Incorrect settings during commissioning may cause unexpected and dangerous motor and system movements.

Possible consequence: death, severe injuries or damage to material assets

- Clear hazardous area.
- Observe safety instructions and safety clearances.

5.2 Before initial switch-on

Prevent injury to persons and damage to material assets. Check the following before switching on the mains voltage:

- · Is the wiring complete and correct?
- · Are there no short circuits and earth faults?
- Is the motor circuit configuration (star/delta) adapted to the output voltage of the inverter?
- Is the motor connected in-phase (direction of rotation)?
- Does the "emergency stop" function of the entire plant operate correctly?

5.3 Initial switch-on / functional test

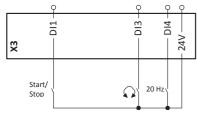
Target: achieve rotation of the motor connected to the inverter as quickly as possible.

Requirements:

- The connected motor matches the inverter in terms of power.
- · The parameter settings comply with the delivery status (Emotron setting).

1. Preparation:

- 1. Wiring of power terminals. (Chapter 4.3 Electrical installation)
- Wire digital inputs X3/DI1 (start enable), X3/DI3 (reversal of rotation direction), and X3/DI4 (preset setpoint 20 Hz).
- 3. Do not connect terminal X3/AI1 (analog setpoint selection) or connect it to GND.



2. Switch on mains and check readiness for operation:

- Switch on mains voltage.
 - 2. Observe LED status displays "RDY" and "ERR" on the front of the inverter:
 - a) If the blue "RDY" LED is blinking and the red "ERR" LED is off, the inverter is ready for operation. The controller is inhibited.

You can now start the drive.

b) If the red "ERR" LED is lit permanently, a fault is pending.

Eliminate the fault before you carry on with the functional test.

LED status displays

| "RDY" LED (blue) | "ERR" LED (red) | Status/meaning | | |
|------------------|-----------------------|------------------------------------------------------------|------------------------------------|--|
| off | off | No supply voltage. | | |
| blinking (1 Hz) | off | Safe torque off (STO) active. | | |
| | blinking fast (4 Hz) | Safe torque off (STO) active. Warning active. | | |
| blinking (2 Hz) | off | Inverter inhibited. | | |
| | lit every 1.5 s for a | Inverter inhibited, no DC-bus voltage. | | |
| | short time | | | |
| | blinking fast (4 Hz) | Inverter inhibited, warning active. | | |
| | on | Inverter inhibited, fault active. | | |
| on | off | Inverter enabled. | The drive rotates according to the | |
| | blinking fast (4 Hz) | Inverter enabled, warning active. | setpoint specified. | |
| | blinking (1 Hz) | Inverter enabled, quick stop as response to a faultactive. | | |

Carrying out the functional test

1. Start drive:

- 1. Enable inverter: X3/DI1 = HIGH.
 - a) If the inverter is equipped with an integrated safety system: X1/SIA = HIGH and X1/SIB = HIGH.
- 2. Activate preset setpoint 1 (20 Hz) as speed setpoint: X3/DI4 = HIGH.

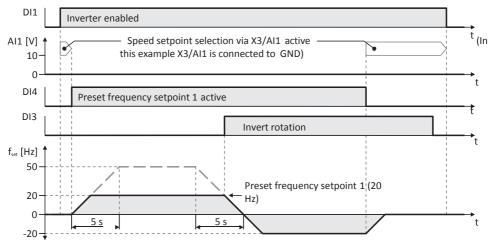
The drive rotates with 20 Hz.

- 3. Optional: activate the function for the reversal of rotation direction.
 - a) X3/DI3 = HIGH.

The drive rotates with 20 Hz in the opposite direction.

b) Deactivate the function for the reversal of rotation direction again: X3/DI3 = LOW.

Speed characteristic (example)



2. Stop drive:

- 1. Deactivate preset setpoint 1 again: X3/DI4 = LOW.
- 2. Inhibit inverter again: X3/DI1 = LOW.

The functional test is completed.

i

The commissioning process of the drive solution is described in a separate commissioning instruction which can be found on the Internet in our download area:

http://www.emotron.com/ services-support/file-archive/

Technical data 6

Standards and operating conditions 6.1

| Conformities | | |
|---------------------------------------|------------------|----------------------------------------------------------|
| CE | 2014/35/EU | Low-Voltage Directive |
| | 2014/30/EU | EMC Directive (reference: CE-typical drive system) |
| EAC | TR TC 004/2011 | Eurasian conformity: Safety of low voltage equipment |
| | TP TC 020/2011 | Eurasian conformity: Electromagnetic compatibility of |
| | | technical means |
| RoHS 2 | 2011/65/EU | Restrictions for the use of specific hazardous materials |
| | | in electric and electronic devices |
| Approvals | | |
| UL | UL 61800-5-1 | in preparation |
| CSA | CSA 22.2 No. 274 | |
| Energy efficiency | | |
| Class IE2 | EN 50598-2 | |
| Type of protection | | |
| IP20 | EN 60529 | |
| Type 1 | NEMA 250 | Protection against contact |
| Insulation resistance | | |
| Overvoltage category III | EN 61800-5-1 | 0 2000 m a.m.s.l. |
| Overvoltage category II | | above 2000 m a.m.s.l. |
| Control circuit isolation | | - |
| Safe mains isolation by double/ | EN 61800-5-1 | |
| reinforced insulation | | |
| Protective measures against | | • |
| Short circuit | | |
| Earth fault | | Earth fault strength depends on the operating status |
| Overvoltage | | |
| Motor stalling | | |
| Motor overtemperature | | PTC or thermal contact, I ² xt monitoring |
| Leakage current | | |
| > 3.5 mA AC, > 10 mA DC | EN 61800-5-1 | Observe regulations and safety instructions! |
| Mains switching | 1 | |
| 3-time mains switching in 1 min | | cyclic, without restrictions |
| Starting current | | |
| ≤ 3 x rated mains current | | |
| Mains systems | | |
| т | | |
| TN | | |
| IT | | Apply the measures described for IT systems! |
| Operation on public supply systems | | |
| Implement measures to limit the radio | | The compliance with the requirements for the |
| interference to be expected: | | machine/plant is the responsibility of the |
| · | | manufacturer of the machine or plant! |
| < 0.5 kW: with mains choke | EN 61000-3-2 | · |
| 0.5 1 kW: With active filter | 1 | |
| > 1 kW at mains current ≤ 16 A: | 1 | |
| without additional measures | | |
| Mains current > 16 A: with mains | EN 61000-3-12 | RSCE: Short-circuit power ratio at the connection |
| choke or mains filter, with | | point of the machine/plant to the public network. |
| | | ,, |
| dimensioning for rated power. Rsce≥ | | |

| Capacitance per unit length | | |
|--------------------------------------|--------------------|-----------------------------------------------------|
| C-core-core/C-core-shield < 75/150 | | ≤ 2,5 mm² / AWG 14 |
| pF/m | | |
| C-core-core/C-core-shield < 150/300 | | ≥ 4 mm² / AWG 12 |
| pF/m | | |
| Electric strength | | |
| Uo/U = 0,6/1,0 kV | | Uo = r.m.s. value external conductor to PE |
| | | U = r.m.s. value external conductor/external |
| U ≥ 600 V | UL | conductor |
| Climate | | |
| 1K3 (-25 +60 °C) | EN 60721-3-1 | Storage |
| 2K3 (-25 +70 °C) | EN 60721-3-2 | Transport |
| 3K3 (-10 +55 °C) | EN 60721-3-3 | Operation |
| | | Operation at a switching frequency of 2 or 4 kHz: |
| | | above +45°C, reduce rated output current by 2.5%/°C |
| | | Operation at a switching frequency of 8 or 16 kHz: |
| | | above +40°C, reduce rated output current by 2.5%/°C |
| Site altitude | | |
| 0 1000 m a.m.s.l. | | |
| 1000 4000 m a.m.s.l. | | Reduce rated output current by 5 %/1000 m |
| Pollution | | |
| Degree of pollution 2 | EN 61800-5-1 | |
| Vibration resistance | | |
| Transport | | |
| 2M2 | EN 60721-3-2 | |
| Operation | | |
| Amplitude 1 mm | Germanischer Lloyd | 5 13.2 Hz |
| acceleration resistant up to 0.7 g | | 13.2 100 Hz |
| Amplitude 0.075 mm | EN 61800-5-1 | 10 57 Hz |
| acceleration resistant up to 1 g | | 57 150 Hz |
| Noise emission | | |
| Category C1 | EN 61800-3 | type-dependent, for motor cable lengths see rated |
| | | data |
| Category C2 | | Motor cable lengths see rated data |
| Noise immunity | | |
| | | |
| Meets requirement in compliance with | EN 61800-3 | |

6.2 Rated data

6.2.1 Connection to the 400 V system

| Inverter | | VS30407P3 | VS30409P5 | VS3040013 | VS3040016 |
|--------------------------|-----|------------------------------------|-----------|-----------|-----------|
| Rated power | kW | 3 | 4 | 5,5 | 7,5 |
| Mains voltage range | V | 3/N/PE AC 360 V 440 V, 45 Hz 55 Hz | | | |
| Operating mode | | S1 | | | |
| Max. ambient temperature | °C | 45 | | | |
| Switching frequency | kHz | 4 | | | |
| Rated mains current | | | | | |
| without mains choke | Α | 9,6 | 12,5 | 17,2 | 20 |
| with mains choke | Α | 6,9 | 9 | 12,4 | 15,7 |
| Rated output current | Α | 7,3 | 9,5 | 13 | 16,5 |
| Motor cable length | | | | 1 | |
| C2 residential area / | m | 20 | | | |
| industrial premises | | | | | |
| Weight | kg | 2,3 3,7 | | | |

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